




# Abhinav Grover

Robotics & ML Engineer

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## Education

### M.A.Sc. - Robotics Eng.

University of Toronto  
Robotics Institute  
Graduation November 2021  
[Publication Link](#)  
GPA: 3.9/4.0

- ▶ (A) State Estimation
- ▶ (A) Perception for Robotics
- ▶ (A) Optimal Control

### B.A.Sc. - Mechatronics Eng.

University of Waterloo  
Graduation April 2019  
GPA: 91.5%

- ▶ (A+) Deep Learning
- ▶ (A) Autonomous Robots
- ▶ (A+) Control Systems

## Skills

Python 3+ yrs.

C/C++ 2+ yrs.

bash/zsh 2+ yrs.

Golang 1+ yrs.

Keras/TF/PyTorch 2+ yrs.

Scikit-learn 2+ yr

ROS 2 yrs.

Linux Development 2 yrs.

## Interests

- ▶ Badminton
- ▶ Tennis
- ▶ Cricket
- ▶ Chess
- ▶ Non-fiction Books

## Relevant Experience

### Machine Learning Engineer | Grocery Pick Team

5 months (Current)

Kindred AI, San Francisco

Building the world's first fully autonomous grocery fulfillment robotic system using *PyTorch* and *Golang*.

### Graduate Research Student | Teaching Assistant

2 Years

STARS lab (Dr. Jonathan Kelly)

University of Toronto

Published a method to detect in-hand object slip using in-expensive tactile sensors for robotic hands, also worked as a teaching assistant for a third year AI course.

### ML Research Intern | Autonomous Vehicles

8 Months

Nvidia Inc., New Jersey

Manager: Joyjit Daw (Recommendation on LinkedIn)

Contributed to the data acquisition infrastructure of Nvidia's self-driving software. Projects also included sensor calibration and vehicle controller tuning.

### Systems Engineering Intern | DRIVE Platform

4 Months

Nvidia Inc., Seattle

Manager: Arun Gona (Recommendation on LinkedIn)

Worked on the OS flashing infrastructure for Nvidia's autonomous driving hardware platform. Implemented incremental flashing to reduce testing delays.

Find more information on [LinkedIn](#) or my [personal website](#).

## Publications

- "Under Pressure: Learning to Detect Slip with Barometric Tactile Sensors", **A. Grover**, C. Grebe, P. Nadeau, and J. Kelly, IEEE Int. Conf. of Robotics and Automation (2022). [Link to page](#).
- "Certifiably Optimal Monocular Hand-Eye Calibration", E. Wise, M. Giamou, S. Khoubyarian, **A. Grover**, and J. Kelly, IEEE Int. Conf. on Multisensor Fusion and Integration (2020). [Link to page](#).

## Relevant Projects

### Accurate Road Segmentation using Camera and LIDAR Data

[Project Link](#)

*Pytorch, OpenCV*

Implemented a Fully Connected Network (FCN) based Road Segmentation pipeline on Audi's A2D2 dataset. Implemented the late and early fusion strategy published by Caltagirone et. al. and achieved an average precision of over 90%. The code, as well as a video, along with a full report are available for further details.

### Failure-Mode Analysis of A Learned Dexterous Hand Controller

[Project Link](#)

*Tensorflow, OpenAI gym, mujoco*

Conducted a failure mode analysis on learned DDPG based policies used to control a dexterous hand with tactile sensors, in an attempt to understand the utility of tactile information. The code, as well as a video, along with a full report are available.

### Invariant EKF SLAM

[Project Link](#)

*MATLAB*

Implemented an Invariant EKF-SLAM method by representing the robot pose as a member of the special euclidean Lie group, with the goal to eliminate the problem of inconsistency. The code, as well as a video, along with a full report are available.